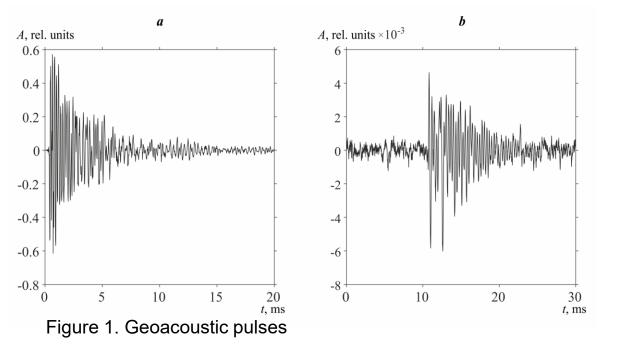
IKIR FEB RAS

Application of adaptive wavelet thresholding to recovery geophysical signal pulse waveforms

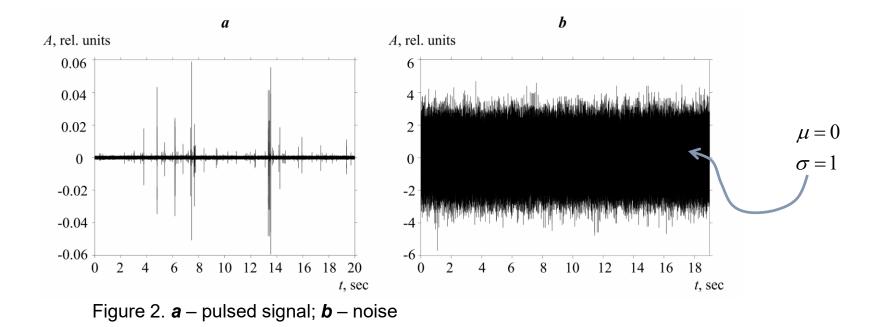
Olga Lukovenkova

Problem



Reasons

- natural noise
- artificial interference
- nonlinearity of receive path
- dynamic range limitations
- quantization errors
- primary hardware processing, etc



Fragments without pulses were selected from the geoacoustic signal recorded in good weather conditions. This noise signal was scaled and shifted.

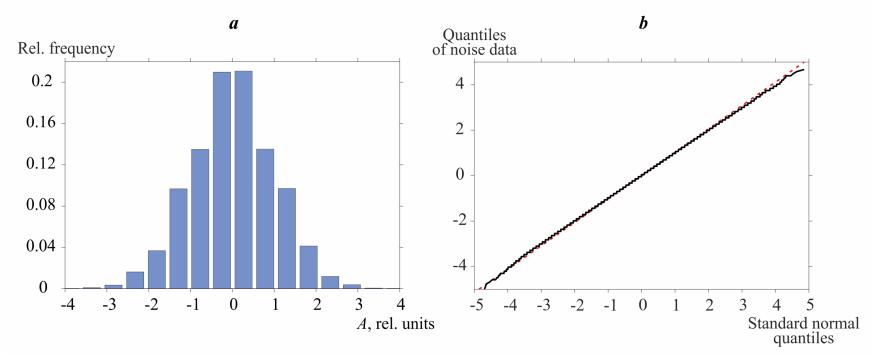


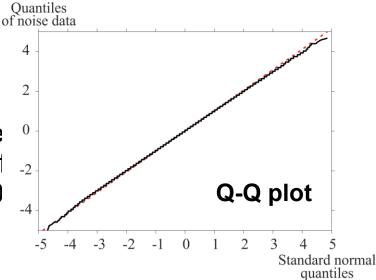
Figure 3. *a* – histogram; *b* – Q-Q plot

Table 1. Applying various statistical test

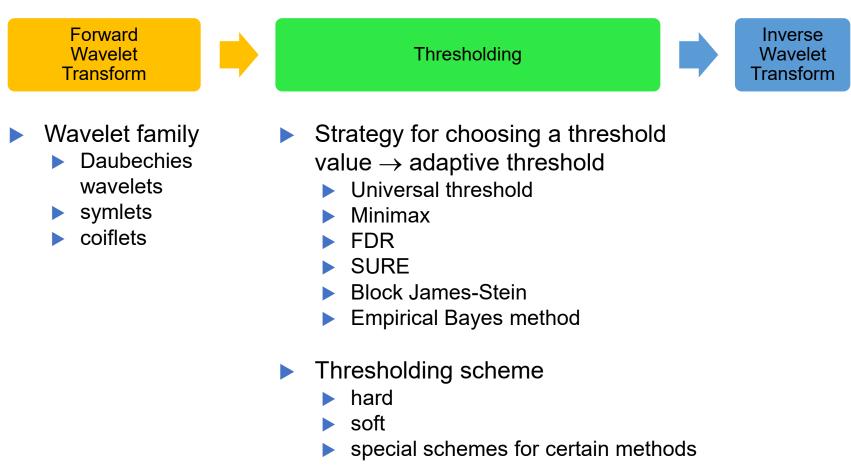
Test	Significance level, α	Sample size, <i>N</i>	Accepted hypothesis, <i>H</i> ₀ or <i>H</i> ₁
Pearson	0.05	500	H ₀
		1000	H ₀
Anderson– Darling	0.05	500	H _o
		1000	H ₁
Lilliefors	0.05	500	H ₀
		1000	H_1

 H_0 – The noise signal amplitudes have the normal distribution $N(\mu, \sigma)$, where μ and σ are estimated from the tested data

- ADC used in the signal registration system has a resolution of 16 bits (65536 levels, values from -1 to 1)
- According to calculations, dynamic range of the formed noise signal contains 112 levels (values from -0.00189 to 0.001526)
- Gaussian noise signal was generated and digitized
- The Wilcoxon–Mann–Whitney te confirmed H_0 (the distributions of both samples are equal) at $\alpha = 0$ for N = 500, 1000



Wavelet thresholding as denoising method



Method selection

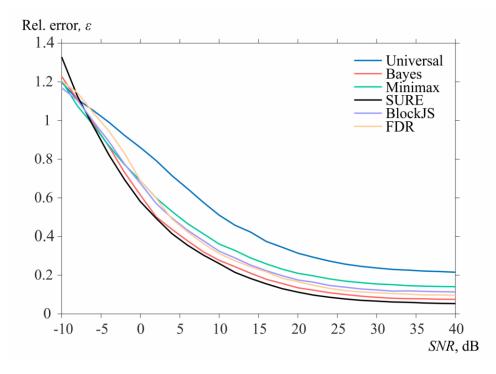


Figure 4. $\varepsilon(SNR)$ plots for different threshold calculation methods

Average relative error of wavelet thresholding

$$\varepsilon = \frac{1}{N} \sum_{i=1}^{N} \frac{\|s_i(t) - \hat{s}_i(t)\|}{\|s_i(t)\|}$$
(1)

where

 $s_i(t)$ is an undistorted pulse

- $\hat{s}_i(t)$ is a pulse after the wavelet thresholding
 - *N* is a total number of processed pulses

Empirical Bayes Method

Mathematics

 $x_i = \mu_i + \epsilon_i \quad (2)$

where

 x_i are detail wavelet coefficients of distorted signal

 μ_i are coefficients of undistorted signal ϵ_i is normally distributed noise

 $f(\mu) = (1-\omega)\delta_0 + \omega\gamma(\mu) \quad \mbox{(3)} \label{eq:f}$ where

ω is the probability that $μ_i = 0$ γ is quasi-Cauchy distribution

Thresholding procedure

- μ_i are evaluated by posterior median $\hat{\mu}(d_i, \omega)$
- μ_i are evaluated by posterior mean $\bar{\mu}(d_i, \omega)$
- determining $t(\omega)$ and soft or hard thresholding

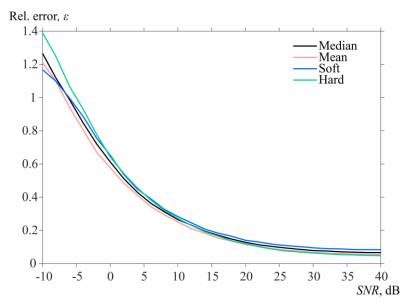


Figure 5. $\epsilon(SNR)$ plots for various thresholding procedures

Wavelet family selection

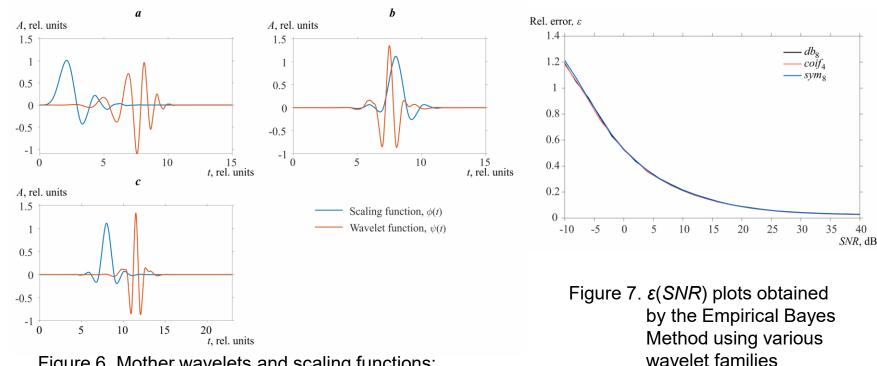
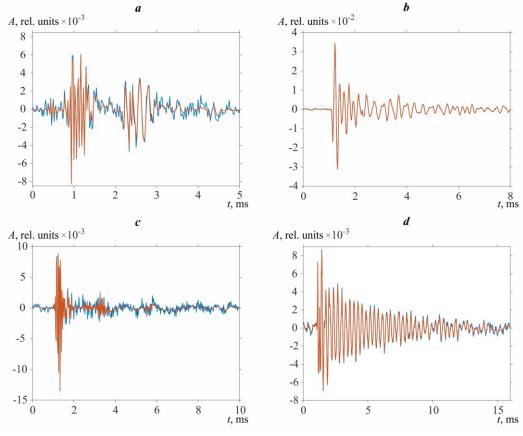


Figure 6. Mother wavelets and scaling functions:

- a eighth-order Daubechies wavelet, db₈;
- \boldsymbol{b} eighth-order symlet, sym₈;
- c forth-order coiflet, coif₄

Approbation



Denoising method

- Empirical Bayes Method
- posterior mean
 - forth-order coiflets

Figure 8. Real data processing

Thank you for your attention

Questions